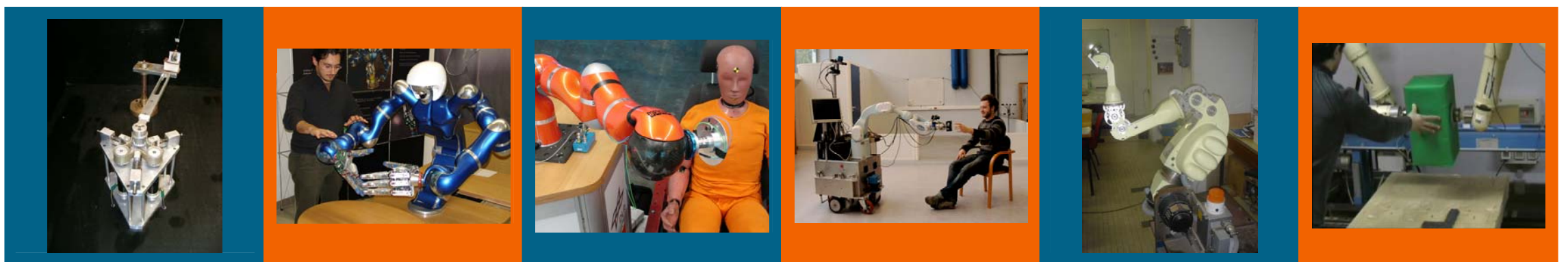




Physical Human-Robot Interaction: DepENDability and Safety

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This project aims at developing robots that can co-exist and co-operate with people, enabling a physical human-robot interaction which is dependable and safe: in a word, to make robots and humans **PHRIENDS**

Centro "E. Piaggio",
Università di Pisa,
Italy

Prof. Antonio Bicchi
bicchi@ing.unipi.it

Institute of Robotics and
Mechatronics, DLR,
Germany

Dr. Alin Albu-Schaeffer
alin.albu-schaeffer@dlr.de

KUKA Roboter GmbH,
Germany

Dr. Rainer Bischoff
rainerbischoff@kuka-roboter.de

LAAS, CNRS,
France

Dr. Rachid Alami
rachid.alami@laas.fr

DIS, Università di Roma
"La Sapienza",
Italy

Prof. Alessandro De Luca
deluca@dis.uniroma1.it

PRISMA Lab/DIS,
Università di Napoli
Federico II, Italy

Prof. Bruno Siciliano
siciliano@unina.it

